

Introduction

This document describes the specifications for a XPS Timer/Counter core for the Processor Local Bus.

The XPS Timer/Counter is a 32-bit timer module that attaches to the PLB bus.

Features

- Connects as a 32-bit slave on PLB V4.6 buses of 32, 64 or 128 bits
- PLB interface with byte-enable support
- Two programmable interval timers with interrupt, event generation, and event capture capabilities
- Configurable counter width
- One Pulse Width Modulation (PWM) output
- Freeze input for halting counters during software debug

LogiCORE™ Facts		
Core Specifics		
Supported Device Family	See EDK Supported Device Families .	
Version of Core	xps_timer	v1.01b
Resources Used		
	Min	Max
Slices	Refer to the Table 9 , Table 10 , Table 11 , Table 12 and Table 13	
LUTs		
FFs		
Block RAMs	N/A	
Provided with Core		
Documentation	Product Specification	
Design File Formats	VHDL	
Constraints File	N/A	
Verification	N/A	
Instantiation Template	N/A	
Reference Designs & application notes	N/A	
Design Tool Requirements		
Xilinx Implementation Tools	See Tools for requirements.	
Verification		
Simulation		
Synthesis		
Support		
Support provided by Xilinx, Inc.		

Functional Description

The Timer/Counter is organized as two identical timer modules as shown in [Figure 2](#). Each timer module has an associated load register that is used to hold either the initial value for the counter for event generation, or a capture value, depending on the mode of the timer.

The *generate value* is used to generate a single interrupt at the expiration of an interval, or a continuous series of interrupts with a programmable interval. The *capture value* is the timer value that has been latched on detection of an external event. The clock rate of the timer modules is SPLB_Clk (no prescaling of the clock is performed). All of the Timer/Counter interrupts are OR'ed together to generate a single external interrupt signal. The interrupt service routine reads the control/status registers to determine the source of the interrupt.

Programming Model

Timer Modes

There are three modes that can be used with the two Timer/Counter modules:

- Generate mode
- Capture mode
- Pulse Width Modulation (PWM) mode.

The modes and their characteristics are described in the following sections.

Generate Mode

In the Generate mode, the value in the load register is loaded into the counter. The counter, when enabled, begins to count up or down, depending on the selection of the UDT bit in the Timer Control Status Register (TCSR). See [Figure 6](#) and [Figure 7](#). On transition of the carry out of the counter, the counter stops or automatically reloads the generate value from the load register and continues counting as selected by the ARHT bit in the TCSR. The TINT bit is set in TCSR and, if enabled, the external GenerateOut signal is driven to 1 for one clock cycle. If enabled, the interrupt signal for the timer is driven to 1 for one clock cycle. This mode is useful for generating repetitive interrupts or external signals with a specified interval.

Characteristics

The generate mode has the following characteristics:

- The value loaded into the load register is called the generate value.
- On startup, the generate value in the load register must be loaded into the counter by setting the Load bit in the Timer Control Status Register (TCSR). This applies whether the counter is set up to Auto Reload or Hold when the interval has expired. Setting the Load bit to '1' loads the counter with the value in the load register. For proper operation, the Load bit must be cleared before the counter is enabled.
- When the ARHT bit (Auto Reload/Hold) is set to '1' and the counter rolls over from all '1's to all '0's when counting up, or conversely from all '0's to all '1's when counting down, the generate value in the load register will be automatically reloaded into the counter and the counter will continue to count. If the GenerateOut signal is enabled (bit GENT in the TCSR), an output pulse will be generated (one clock period in width). This is useful for generating a repetitive pulse train with a specified period.
- When the ARHT bit (Auto Reload/Hold) is set to '0' and the counter rolls over from all '1's to all '0's, when counting up, or conversely, from all '0's to all '1's, when counting down, the counter will hold at the current value and will not reload the generate value. If the generate out signal is enabled (bit GENT in the TCSR), an output pulse of one clock period in width will be generated. This is useful for a one-shot pulse that is to be generated after a specified period of time.

- The counter can be set up to count either up or down as determined by the selection of the UDT bit in the TCSR. If the counter is set up as a down counter, the generate value is the number of clocks in the timing interval. The period of the GenerateOut signal is the generate value times the clock period.
- When the counter is set to count down,

$$\text{TIMING_INTERVAL} = (\text{TLR}_x + 2) \times \text{PLB_CLOCK_PERIOD}$$
- When the counter is set to count up,

$$\text{TIMING_INTERVAL} = (\text{MAX_COUNT} - \text{TLR}_x + 2) \times \text{PLB_CLOCK_PERIOD},$$
 where MAX_COUNT is the maximum count value of the counter, such as 0xFFFFFFFF for a 32-bit counter.
- The GenerateOut signals can be configured as high-true or low-true.

Capture Mode

In Capture Mode, the value of the counter is stored in the load register when the external capture signal is asserted. The TINT bit is also set in the Timer Control Status Register (TCSR) on detection of the capture event. The counter can be configured as an up or down counter for this mode as determined by the selection of the UDT bit in TCSR. The ARHT bit controls whether the capture value is overwritten with a new capture value before the previous TINT flag is cleared. This mode is useful for time tagging external events while simultaneously generating an interrupt.

Characteristics

Capture Mode has the following characteristics:

- The capture signal can be configured to be low-true or high-true.
- The capture signal is sampled within the Timer/Counter with the SPLB_Clk. The capture event is defined as the transition on the sampled signal to the asserted state. For example, if the capture signal is defined to be high-true, then the capture event is when the sampled signal, synchronized to the SPLB_Clk, transitions from '0' to '1'.
- When the capture event occurs, the counter value is written to the load register. This value is called the capture value.
- When the ARHT bit (Auto Reload/Hold) is set to '0' and the capture event occurs, the capture value is written to the Load Register which holds the capture value until the load register is read. If the load register is not read, subsequent capture events will not update the load register, and will be lost.
- When the ARHT bit (Auto Reload/Hold) is set to '1', and the capture event occurs, the capture value is always written to the load register. Subsequent capture events will update the load register and will overwrite the previous value, whether it has been read or not.
- The counter can be set up to count either up or down as determined by the selection of the UDT bit in the Timer Control Status Register (TCSR).

Pulse Width Modulation (PWM) Mode

In PWM mode, two timer/counters are used as a pair to produce an output signal (PWM0) with a specified frequency and duty factor. Timer0 sets the period and Timer1 sets the high time for the PWM0 output.

Characteristics

PWM Mode has the following characteristics:

- The mode for both Timer0 and Timer1 must be set to Generate Mode (bit MDT in the TCSR set to '0').
- The PWMA0 bit in TCSR0 and PWMB0 bit in TCSR1 must be set to '1' to enable PWM mode.

- The GenerateOut signals must be enabled in the TCSR (bit GENT set to '1'). The PWM0 signal is generated from the GenerateOut signals of Timer0 and Timer1, so these signals must be enabled in both timer/counters.
- The assertion level of the GenerateOut signals for both timers in the pair must be set to '1'. This is done by setting C_GEN0_ASSERT and C_GEN1_ASSERT to '1'.
- The counter can be set to count up or down.

Setting the PWM Period and Duty Factor

The PWM period is determined by the generate value in Timer0's load register (TLR0). The PWM high time is determined by the generate value in Timer1's load register (TLR1). The period and duty factor are calculated as follows:

When counters are configured to count up (UDT = '0'):

$$\begin{aligned} \text{PWM_PERIOD} &= (\text{MAX_COUNT} - \text{TLR0} + 2) \times \text{PLB_CLOCK_PERIOD} \\ \text{PWM_HIGH_TIME} &= (\text{MAX_COUNT} - \text{TLR1} + 2) \times \text{PLB_CLOCK_PERIOD} \end{aligned}$$

When counters are configured to count down (UDT = '1'):

$$\begin{aligned} \text{PWM_PERIOD} &= (\text{TLR0} + 2) \times \text{PLB_CLOCK_PERIOD} \\ \text{PWM_HIGH_TIME} &= (\text{TLR1} + 2) \times \text{PLB_CLOCK_PERIOD} \end{aligned}$$

where MAX_COUNT is the maximum count value for the counter, such as 0xFFFFFFFF for a 32-bit counter.

Interrupts

The TC interrupt signals can be enabled or disabled with the ENIT bit in the TCSR. The interrupt status bit (TINT) in the TCSR cannot be disabled and always reflects the current state of the timer interrupt. In Generate Mode, a timer interrupt is caused by the counter rolling over (the same condition used to reload the counter when ARHT is set to '1'). In Capture Mode, the interrupt event is the capture event. Characteristics of the interrupts are:

- Interrupt events can only occur when the timer is enabled. In Capture Mode, this prevents interrupts from occurring before the timer is enabled.
- The interrupt signal goes high when the interrupt condition is met and the interrupt is enabled in the TCSR. The interrupt is asserted when the interrupt signal is high.
- A single interrupt signal is provided. The interrupt signal is the OR of the interrupts from the two counters. The interrupt service routine must poll the TCSR's to determine the source or sources of the interrupt.
- The interrupt status bit (TINT in the TCSR) can only be cleared by writing a '1' to it. Writing a '0' to it has no effect on the bit. Since the interrupt condition is an edge (the counter rollover or the capture event), it can be cleared at any time and will not indicate an interrupt condition until the next interrupt event.

The top level block diagram of the XPS Timer/Counter is shown in [Figure 1](#).

The top level modules of the XPS Timer/Counter are:

- PLB Interface Module

- Timer/Counter

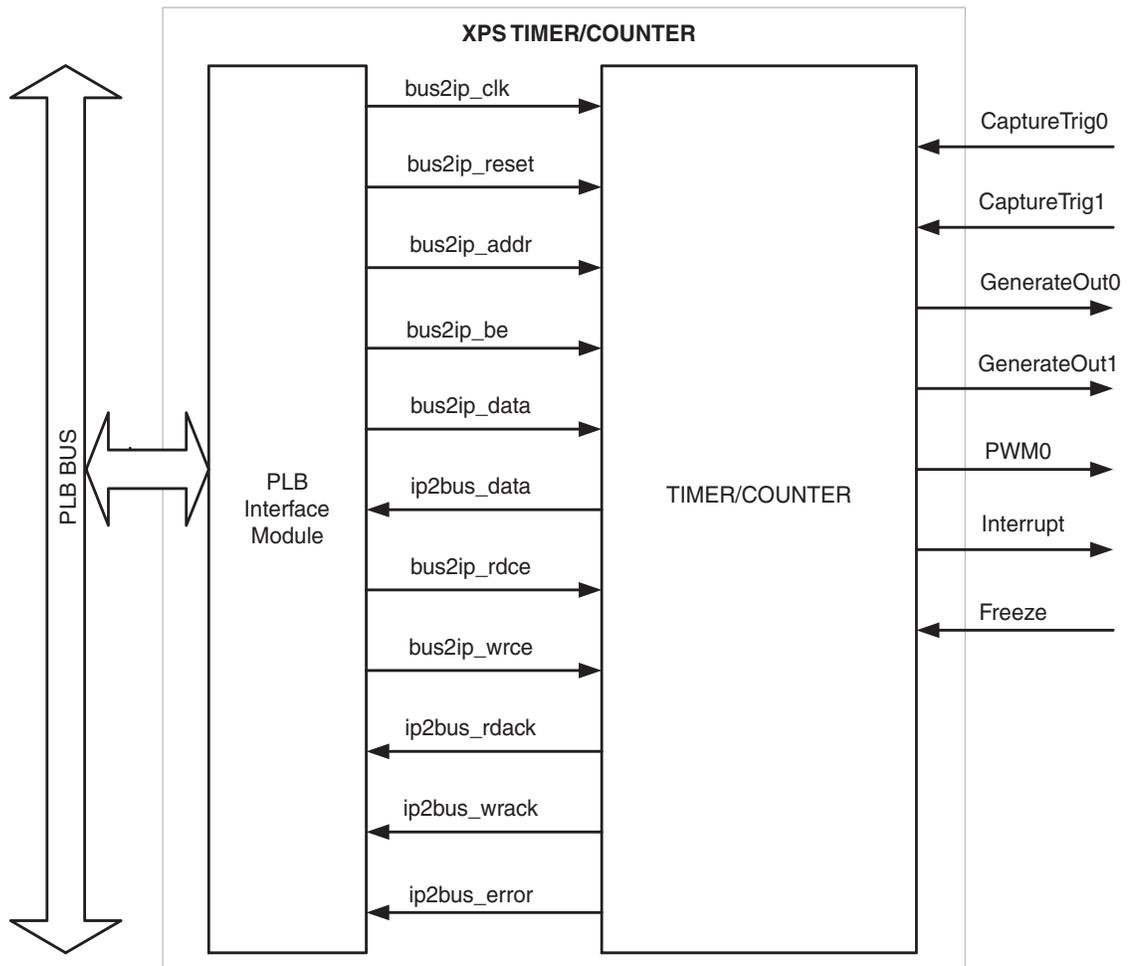


Figure 1: XPS Timer/Counter Top-Level Block Diagram

The detailed block diagram of the XPS Timer/Counter is shown in [Figure 2](#).

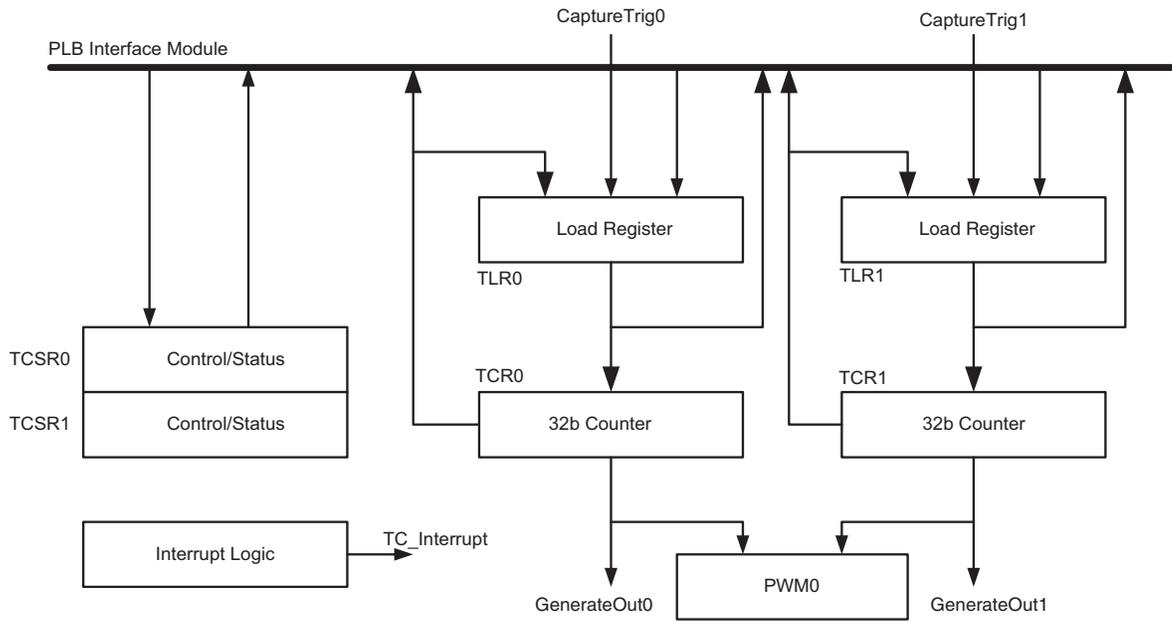


Figure 2: XPS Timer/Counter Detailed Block Diagram

XPS Timer/Counter I/O Signals

The XPS Timer/Counter I/O signals are listed and described in [Table 1](#).

Table 1: XPS Timer/Counter I/O Signal Description

Port	Signal Name	Interface	I/O	Initial Status	Description
System Signals					
P1	SPLB_Clk	PLB	I	-	PLB clock
P2	SPLB_Rst	PLB	I	-	PLB reset, active high
PLB Slave Interface Input Signals					
P3	PLB_ABus[0 to C_SPLB_AWIDTH - 1]	PLB	I	-	PLB address bus
P4	PLB_PAVValid	PLB	I	-	PLB primary address valid
P5	PLB_masterID[0 : C_SPLB_MID_WIDTH - 1]	PLB	I	-	PLB current master identifier
P6	PLB_RNW	PLB	I	-	PLB read not write
P7	PLB_BE[0 : (C_SPLB_DWIDTH/8) - 1]	PLB	I	-	PLB byte enables
P8	PLB_size[0 : 3]	PLB	I	-	PLB byte enables
P9	PLB_type[0 : 2]	PLB	I	-	PLB transfer type

Table 1: XPS Timer/Counter I/O Signal Description (Contd)

Port	Signal Name	Interface	I/O	Initial Status	Description
P10	PLB_wrDBus[0 : C_SPLB_DWIDTH - 1]	PLB	I	-	PLB write data bus
Unused PLB Slave Interface Input Signals					
P11	PLB_UABus[0 to C_SPLB_AWIDTH - 1]	PLB	I	-	PLB upper address bits
P12	PLB_SAVAlid	PLB	I	-	PLB secondary address valid
P13	PLB_rdPrim	PLB	I	-	PLB secondary to primary read request indicator
P14	PLB_wrPrim	PLB	I	-	PLB secondary to primary write request indicator
P15	PLB_abort	PLB	I	-	PLB abort bus request
P16	PLB_busLock	PLB	I	-	PLB bus lock
P17	PLB_MSize	PLB	I	-	PLB data bus port width indicator
P18	PLB_lockErr	PLB	I	-	PLB lock error
P19	PLB_wrBurst	PLB	I	-	PLB burst write transfer
P20	PLB_rdBurst	PLB	I	-	PLB burst read transfer
P21	PLB_wrPendReq	PLB	I	-	PLB pending bus write request
P22	PLB_rdPendReq	PLB	I	-	PLB pending bus read request
P23	PLB_wrPendPri[0 : 1]	PLB	I	-	PLB pending write request priority
P24	PLB_rdPendPri[0 : 1]	PLB	I	-	PLB pending read request priority
P25	PLB_reqPri[0 : 1]	PLB	I	-	PLB current request priority
P26	PLB_TAtribute	PLB	I	-	PLB transfer attribute
PLB Slave Interface Output Signals					
P27	SI_addrAck	PLB	O	0	Slave address acknowledge
P28	SI_SSize[0 : 1]	PLB	O	0	Slave data bus port size
P29	SI_wait	PLB	O	0	Slave wait
P30	SI_rearbitrate	PLB	O	0	Slave bus rearbitrate
P31	SI_wrDAck	PLB	O	0	Slave write data acknowledge
P32	SI_wrComp	PLB	O	0	Slave write transfer complete
P33	SI_rdDBus[0 : C_SPLB_DWIDTH - 1]	PLB	O	0	Slave read data bus
P34	SI_rdDAck	PLB	O	0	Slave read data acknowledge
P35	SI_rdComp	PLB	O	0	Slave read transfer complete

Table 1: XPS Timer/Counter I/O Signal Description (Contd)

Port	Signal Name	Interface	I/O	Initial Status	Description
P36	SI_MBusy[0 : C_SPLB_NUM_MASTERS - 1]	PLB	O	0	Slave busy
P37	SI_MWrErr[0 : C_SPLB_NUM_MASTERS - 1]	PLB	O	0	Slave write error
P38	SI_MRdErr[0 : C_SPLB_NUM_MASTERS - 1]	PLB	O	0	Slave read error
Unused PLB Slave interface Output Signals					
P39	SI_wrBTerm	PLB	O	0	Slave terminate write burst transfer
P40	SI_rdWdAddr[0 : 3]	PLB	O	0	Slave read word address
P41	SI_rdBTerm	PLB	O	0	Slave terminate read burst transfer
P42	SI_MIRQ[0 : C_SPLB_NUM_MASTERS - 1]	PLB	O	0	Master interrupt request
XPS Timer/Counter Signals					
P43	CaptureTrig0	Ext.	I	-	Capture Trigger 0
P44	CaptureTrig1	Ext.	I	-	Capture Trigger 1
P45	Freeze	Ext.	I	-	Freeze Count Value
P46	GenerateOut0	Ext.	O	0	Generate Output 0
P47	GenerateOut1	Ext.	O	0	Generate Output 1
P48	PWM0	Ext.	O	0	Pulse Width Modulation Output 0
P49	Interrupt	Ext.	O	0	Interrupt

XPS Timer/Counter Design Parameters

To allow the user to create the XPS Timer/Counter that is uniquely tailored for the user's system, certain features can be parameterized in the XPS Timer/Counter design. This allows the user to have a design that only utilizes the resources required by the system and operating at the best possible performance. The features that are parameterizable in the XPS Timer/Counter are as shown in [Table 2](#).

Table 2: XPS Timer/Counter Design Parameters

Generic	Feature / Description	Parameter Name	Allowable Values	Default Value	VHDL Type
System Parameters					
G1	Target FPGA family	C_FAMILY	See C_FAMILY parameter values .		string
XPS Timer/Counter Parameter					
G2	The width in bits of the counters in the XPS Timer/Counter	C_COUNT_WIDTH	8 - 32	32	integer

Table 2: XPS Timer/Counter Design Parameters (Contd)

Generic	Feature / Description	Parameter Name	Allowable Values	Default Value	VHDL Type
G3	Number of Timer modules	C_ONE_TIMER_ONLY	0 = Two timers are present 1 = One timer is present (No PWM mode)	0	integer
G4	Assertion level for CaptureTrig0	C_TRIG0_ASSERT	'0' = CaptureTrig0 input is low-true '1' = CaptureTrig0 input is high-true	1	std_logic
G5	Assertion level for CaptureTrig1	C_TRIG1_ASSERT	'0' = CaptureTrig1 input is low-true '1' = CaptureTrig1 input is high-true	1	std_logic
G6	Assertion level for GenerateOut0	C_GEN0_ASSERT	'0' = GenerateOut0 output is low-true '1' = GenerateOut0 output is high-true	1	std_logic
G7	Assertion level for GenerateOut1	C_GEN1_ASSERT	'0' = GenerateOut1 output is low-true '1' = GenerateOut1 output is high-true	1	std_logic
PLB Parameter					
G8	PLB address width	C_SPLB_AWIDTH	32	32	integer
G9	PLB data width	C_SPLB_DWIDTH	32, 64, 128	32	integer
G10	Selects point-to-point or shared PLB topology	C_SPLB_P2P	0 = Shared Bus Topology 1 = Point-to-Point Bus Topology	0	integer
G11	PLB Master ID Bus Width	C_SPLB_MID_WIDTH	$\log_2(\text{C_SPLB_NUM_MASTERS})$ with a minimum value of 1	3	integer
G12	Number of PLB Masters	C_SPLB_NUM_MASTERS	1 - 16	8	integer
G13	Width of the Slave Data Bus	C_SPLB_NATIVE_DWIDTH	32	32	integer
G14	PLB burst support	C_SPLB_SUPPORT_BURSTS	0	0	integer
G15	Base address for XPS Timer/Counter	C_BASEADDR	Valid address	Note ^[1]	std_logic_vector

Table 2: XPS Timer/Counter Design Parameters (Contd)

Generic	Feature / Description	Parameter Name	Allowable Values	Default Value	VHDL Type
G16	High address for XPS Timer/Counter	C_HIGHADDR	Valid address	Note ^[2]	std_logic_vector
Notes: 1. Indicates the base address of this peripheral expressed as a std_logic_vector. C_BASEADDR must be a multiple of the address-range size and the address-range size, C_HIGHADDR - C_BASEADDR + 1, must be a power of two. 2. C_HIGHADDR must be chosen large enough to accommodate the XPS Timer/Counter registers while also guaranteeing a power-of-two address-range size.					

XPS Timer/Counter Parameter Port Dependencies

The dependencies between the XPS Timer/Counter design parameters and the I/O ports are shown in Table 3. The width of the XPS Timer/Counter signals depend on some of the parameters. In addition, when certain features are parameterized away, the related logic is remove.

Table 3: Parameter - Port Dependencies

Generic or Port	Name	Affects	Depends	Description
Design Parameters				
G8	C_SPLB_AWIDTH	P3, P11	-	The PLB address width parameter sets the width of the PLB address bus
G9	C_SPLB_DWIDTH	P7, P10, P33	-	The SPLB data width parameter affects the number of byte enables configured for the SPLB data bus, width of the SPLB data bus and the width of the SPLB slave read data bus
G11	C_SPLB_MID_WIDTH	P5	G12	The PLB Master ID Bus Width should be $\log_2(\text{C_SPLB_NUM_MASTERS})$
G12	C_SPLB_NUM_MASTERS	P36, P37, P38, P42	-	Number of PLB Masters
I/O Signals				
P3	PLB_ABus	-	G8	The PLB address bus width is determined by the C_SPLB_AWIDTH parameter
P5	PLB_masterID	-	G11	The PLB master ID is determined by the C_SPLB_MID_WIDTH parameter
P7	PLB_BE	-	G9	The number of byte enables for the PLB data bus is determined by the C_SPLB_DWIDTH parameter
P10	PLB_wrDBus	-	G9	The PLB data bus width is determined by the C_SPLB_DWIDTH parameter
P11	PLB_UABus	-	G8	The width of the PLB upper address bits is determined by the C_SPLB_AWIDTH parameter
P33	SI_rdDBus	-	G9	The width of the PLB slave read data bus is determined by the C_SPLB_DWIDTH parameter
P36	SI_MBusy	-	G12	The width of PLB slave busy is determined by the C_SPLB_NUM_MASTERS parameter

Table 3: Parameter - Port Dependencies (Contd)

Generic or Port	Name	Affects	Depends	Description
P37	SI_MWrErr	-	G12	The width of PLB slave write error is determined by the C_SPLB_NUM_MASTERS parameter
P38	SI_MRdErr	-	G12	The width of PLB slave read error is determined by the C_SPLB_NUM_MASTERS parameter
P42	SI_MIRQ	-	G12	The width of Master interrupt request is determined by the C_SPLB_NUM_MASTERS parameter

Register Data Types and Organization

Timer Counter registers are accessed as one of the following types:

- Byte (8 bits)
- Half word (2 bytes)
- Word (4 bytes)

The XPS Timer/Counter registers are organized as big-endian data. The bit and byte labeling for the big-endian data types is shown in the **Figure 3**.

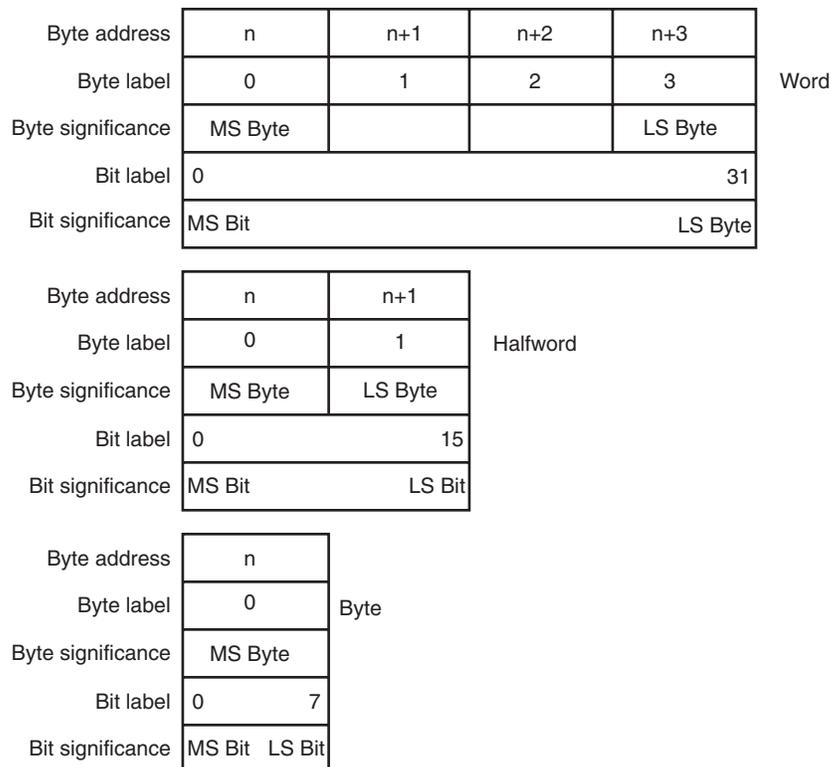


Figure 3: Big-Endian Data Types

Register Descriptions

The addresses of the XPS Timer/ Counter registers are shown in the [Table 4](#):

Table 4: XPS Timer/Counter Register Address Map

Register	Address (Hex)	Size	Type	Description
TCSR0	C_BASEADDR + 0x00	Word	Read/Write	Control/Status Register 0
TLR0	C_BASEADDR + 0x04	Word	Read/Write	Load Register 0
TCR0	C_BASEADDR + 0x08	Word	Read	Timer/Counter Register 0
TCSR1	C_BASEADDR + 0x10	Word	Read/Write	Control/Status Register 1
TLR1	C_BASEADDR + 0x14	Word	Read/Write	Load Register 1
TCR1	C_BASEADDR + 0x18	Word	Read	Timer/Counter Register 1

Load Register (TLR0 and TLR1)

When the counter width has been configured as less than 32 bits, the load register value is right-justified in TLR0 and TLR1. The least-significant counter bit is always mapped to load register bit 31. The [Figure 4](#) and [Table 5](#)

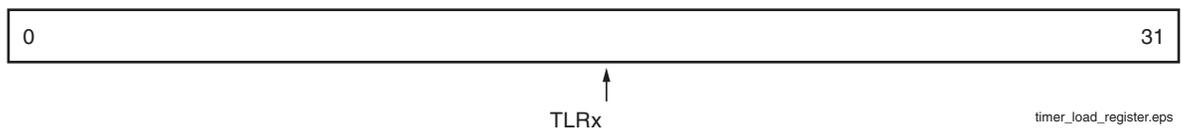


Figure 4: Timer/Counter Load Register (TLR)

shows the load register.

Table 5: Timer/Counter Load Register

Bits	Name	Description	Reset Value
0 - 31	Timer/Counter Load Register	Timer/Counter Load register	0

Timer/Counter Register (TCR0 and TCR1)

When the counter width has been configured as less than 32 bits, the count value is right-justified in TCR0 and TCR1. The least-significant counter bit is always mapped to Timer/Counter Register bit 31. The [Figure 5](#) and [Table 6](#) shows the Timer/counter register

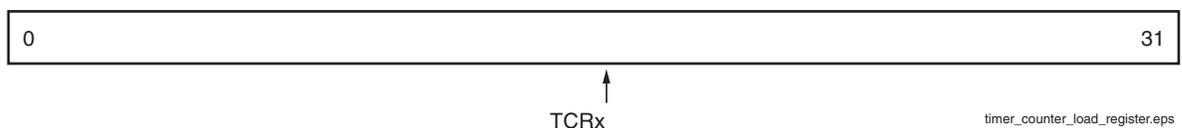


Figure 5: Timer/Counter Register (TCR)

Table 6: Timer/Counter Register

Bits	Name	Description	Reset Value
0 - 31	Timer/Counter Register	Timer/Counter register	0

Control/Status Register 0 (TCSR0)

The Figure 6 and Table 7 shows the Control/Status register 0. Control/Status Register 0 contains the control and status bits for timer module 0.

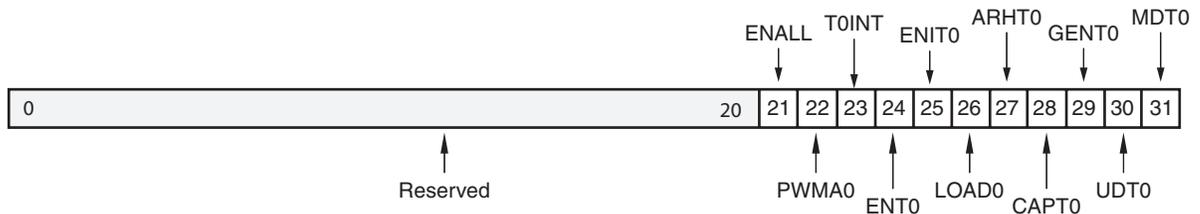


Figure 6: Timer Control/Status Register 0 (TCSR0)

Table 7: Control/Status Register 0 (TCSR0)

Bits	Name	Description	Reset Value
0 - 20	Reserved	Reserved	-
21	ENALL	Enable All Timers 0 = No effect on timers 1 = Enable all timers (counters run) This bit is mirrored in all control/status registers and is used to enable all counters simultaneously. Writing a '1' to this bit sets ENALL, ENT0, and ENT1. Writing a '0' to this register clears ENALL but has no effect on ENT0 and ENT1.	0
22	PWMA0	Enable Pulse Width Modulation for Timer0 0 = Disable pulse width modulation 1 = Enable pulse width modulation PWM requires using Timer0 and Timer1 together as a pair. Timer0 sets the period of the PWM output, and Timer1 sets the high time for the PWM output. For PWM Mode, MDT0 and MDT1 must be '0' and C_GEN0_ASSERT and C_GEN1_ASSERT must be '1'.	0
23	T0INT	Timer0 Interrupt Indicates that the condition for an interrupt on this timer has occurred. If the timer mode is capture and the timer is enabled, this bit indicates a capture has occurred. If the mode is generate, this bit indicates the counter has rolled over. Must be cleared by writing a '1'. <i>Read:</i> 0 = No interrupt has occurred 1 = Interrupt has occurred <i>Write:</i> 0 = No change in state of T0INT 1 = Clear T0INT (clear to '0')	0

Table 7: Control/Status Register 0 (TCSR0) (Contd)

Bits	Name	Description	Reset Value
24	ENT0	Enable Timer0 0 = Disable timer (counter halts) 1 = Enable timer (counter runs)	0
25	ENIT0	Enable Interrupt for Timer0 Enables the assertion of the interrupt signal for this timer. Has no effect on the interrupt flag in TCSR0. 0 = Disable interrupt signal 1 = Enable interrupt signal	0
26	LOAD0	Load Timer0 0 = No load 1 = Loads timer with value in TLR0	0
27	ARHT0	Auto Reload/Hold Timer0 When the timer is in Generate Mode, this bit determines whether the counter reloads the generate value and continues running or holds at the termination value. In Capture Mode, this bit determines whether a new capture trigger overwrites the previous captured value or if the previous value is held. 0 = Hold counter or capture value 1 = Reload generate value or overwrite capture value	0
28	CAPT0	Enable External Capture Trigger Timer0 0 = Disables external capture trigger 1 = Enables external capture trigger	0
29	GENT0	Enable External Generate Signal Timer0 0 = Disables external generate signal 1 = Enables external generate signal	0
30	UDT0	Up/Down Count Timer0 0 = Timer functions as up counter 1 = Timer functions as down counter	0
31	MDT0	Timer0 Mode See the Timer Modes section. 0 = Timer mode is generate 1 = Timer mode is capture	0

Control/Status Register 1 (TCSR1)

The Figure 7 and Table 8 shows the Control/Status register 1. Control/Status Register 1 contains the control and status bits for timer module 1.

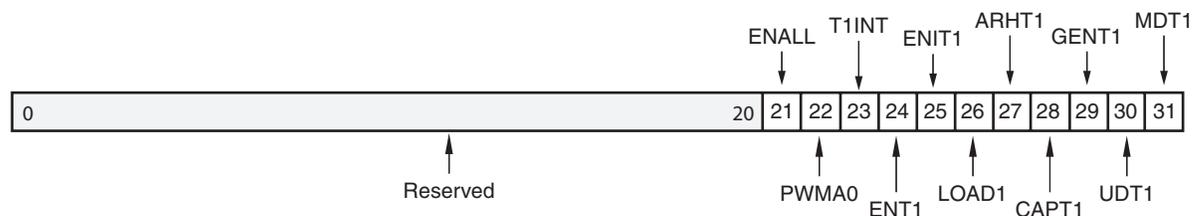


Figure 7: Timer/Status Control Register 1 (TCSR1)

Table 8: Control/Status Register 1 (TCSR1)

Bits	Name	Description	Reset Value
0 - 20	Reserved	Reserved	-
21	ENALL	Enable All Timers 0 = No effect on timers 1 = Enable all timers (counters run) This bit is mirrored in all control/status registers and is used to enable all counters simultaneously. Writing a '1' to this bit sets ENALL, ENT0, and ENT1. Writing a '0' to this register clears ENALL but has no effect on ENT0 and ENT1.	0
22	PWMB0	Enable Pulse Width Modulation for Timer1 0 = Disable pulse width modulation 1 = Enable pulse width modulation PWM requires using Timer0 and Timer1 together as a pair. Timer0 sets the period of the PWM output, and Timer1 sets the high time for the PWM output. For PWM Mode, MDT0 and MDT1 must be '0' and C_GEN0_ASSERT and C_GEN1_ASSERT must be '1'.	0
23	T1INT	Timer1 Interrupt Indicates that the condition for an interrupt on this timer has occurred. If the timer mode is capture and the timer is enabled, this bit indicates a capture has occurred. If the mode is generate, this bit indicates the counter has rolled over. Must be cleared by writing a '1'. <i>Read:</i> 0 = No interrupt has occurred 1 = Interrupt has occurred <i>Write:</i> 0 = No change in state of T1INT 1 = Clear T1INT (clear to '0')	0
24	ENT1	Enable Timer1 0 = Disable timer (counter halts) 1 = Enable timer (counter runs)	0
25	ENIT1	Enable Interrupt for Timer1 Enables the assertion of the interrupt signal for this timer. Has no effect on the interrupt flag in TCSR1. 0 = Disable interrupt signal 1 = Enable interrupt signal	0
26	LOAD1	Load Timer1 0 = No load 1 = Loads timer with value in TLR1	0
27	ARHT1	Auto Reload/Hold Timer1 When the timer is in generate mode, this bit determines whether the counter reloads the generate value and continues running or holds at the termination value. In capture mode, this bit determines whether a new capture trigger overwrites the previous captured value or if the previous value is held until it is read. 0 = Hold counter or capture value 1 = Reload generate value or overwrite capture value	0

Table 8: Control/Status Register 1 (TCSR1) (Contd)

Bits	Name	Description	Reset Value
28	CAPT1	Enable External Capture Trigger Timer1 0 = Disables external capture trigger 1 = Enables external capture trigger	0
29	GENT1	Enable External Generate Signal Timer1 0 = Disables external generate signal 1 = Enables external generate signal	0
30	UDT1	Up/Down Count Timer1 0 = Timer functions as up counter 1 = Timer functions as down counter	0
31	MDT1	Timer1 Mode See the Timer Modes section. 0 = Timer mode is generate 1 = Timer mode is capture	0

Implementation

Target Technology

The target technology is an FPGA listed in [EDK Supported Device Families](#).

Device Utilization and Performance Benchmarks

Core Performance

Since the XPS Timer/Counter core will be used with other design modules in the FPGA, the utilization and timing numbers reported in this section are estimates only. System-level results will vary.

The XPS Timer/Counter resource utilization for various parameter combinations measured with Virtex-4 as the target device is detailed in [Table 9](#).

The XPS Timer/Counter resource utilization for various parameter combinations measured with Virtex-5 as the target device is detailed in [Table 10](#).

The XPS Timer/Counter resource utilization for various parameter combinations measured with Spartan-3 as the target device is detailed in [Table 11](#).

The XPS Timer/Counter resource utilization for various parameter combinations measured with Spartan-6 as the target device is detailed in [Table 12](#).

The XPS Timer/Counter resource utilization for various parameter combinations measured with Virtex-6 as the target device is detailed in [Table 13](#).

Table 9: Performance and Resource Utilization Benchmarks Virtex-4 (xc4vlx25-ff1148-11)

Parameter Values		Device Resources			Performance
C_ONE_TIMER_ONLY	C_COUNT_WIDTH	Slices	Slice Flip-Flops	LUTs	f _{MAX} (MHz)
0	32	226	221	385	209
0	16	155	137	268	218
0	8	123	100	206	204

Table 9: Performance and Resource Utilization Benchmarks Virtex-4 (xc4vlx25-ff1148-11) (Contd)

Parameter Values		Device Resources			Performance
C_ONE_TIMER_ONLY	C_COUNT_WIDTH	Slices	Slice Flip-Flops	LUTs	f _{MAX} (MHz)
1	32	165	150	267	201
1	16	114	100	185	221
1	8	90	79	144	211

Table 10: Performance and Resource Utilization Benchmarks Virtex-5 (xc5vlx30-ff1153-2)

Parameter Values		Device Resources		Performance
C_ONE_TIMER_ONLY	C_COUNT_WIDTH	Slice Flip-Flops	LUTs	f _{MAX} (MHz)
0	32	221	313	243
0	16	153	242	248
0	8	121	205	245
1	32	150	212	250
1	16	116	178	236
1	8	100	159	247

Table 11: Performance and Resource Utilization Benchmarks Spartan-3 (xc3s1500-fg676-5)

Parameter Values		Device Resources			Performance
C_ONE_TIMER_ONLY	C_COUNT_WIDTH	Slices	Slice Flip-Flops	LUTs	f _{MAX} (MHz)
0	32	226	220	387	111
0	16	155	136	270	125
0	8	122	99	208	124
1	32	165	149	269	114
1	16	113	99	186	139
1	8	90	78	146	146

Table 12: Performance and Resource Utilization Benchmarks Spartan-6 (xc6slx45-fgg484-2)

Parameter Values		Device Resources		Performance
C_ONE_TIMER_ONLY	C_COUNT_WIDTH	Slice Flip-Flops	LUTs	f _{MAX} (MHz)
0	32	186	283	105
0	16	121	186	108
0	8	89	151	127
1	32	117	171	120
1	16	84	126	126
1	8	68	109	128

Table 13: Performance and Resource Utilization Benchmarks Virtex-6 (xc6vlx195t-ff11562-1)

Parameter Values		Device Resources		Performance
C_ONE_TIMER_ONLY	C_COUNT_WIDTH	Slice Flip-Flops	LUTs	f _{MAX} (MHz)
0	32	186	365	203
0	16	121	232	202
0	8	89	174	203
1	32	117	217	202
1	16	84	149	201
1	8	68	124	209

System Performance

To measure the system performance (F_{MAX}) of this core, this core was added to a Virtex-4 system, a Virtex-5 system, Spartan-3A system as the Device Under Test (DUT) as shown in Figure 8, Figure 9 and Figure 10.

Because the XPS Timer/Counter core will be used with other design modules in the FPGA, the utilization and timing numbers reported in this section are estimates only. When this core is combined with other designs in the system, the utilization of FPGA resources and timing of the core design will vary from the results reported here.

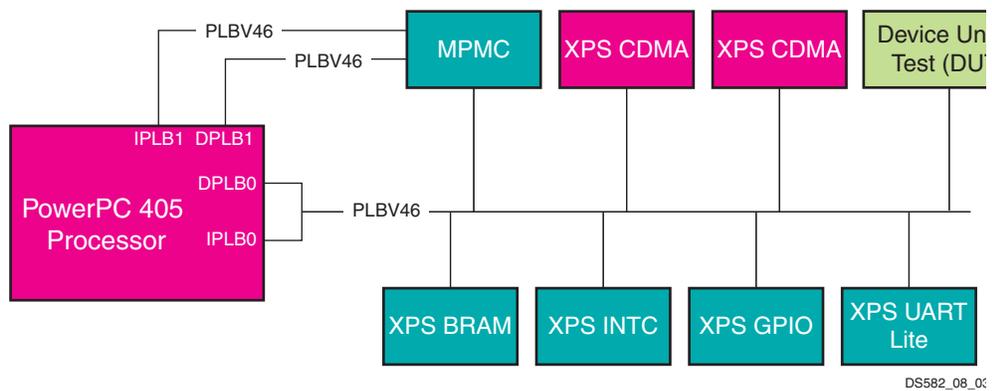


Figure 8: Virtex-4 FX System

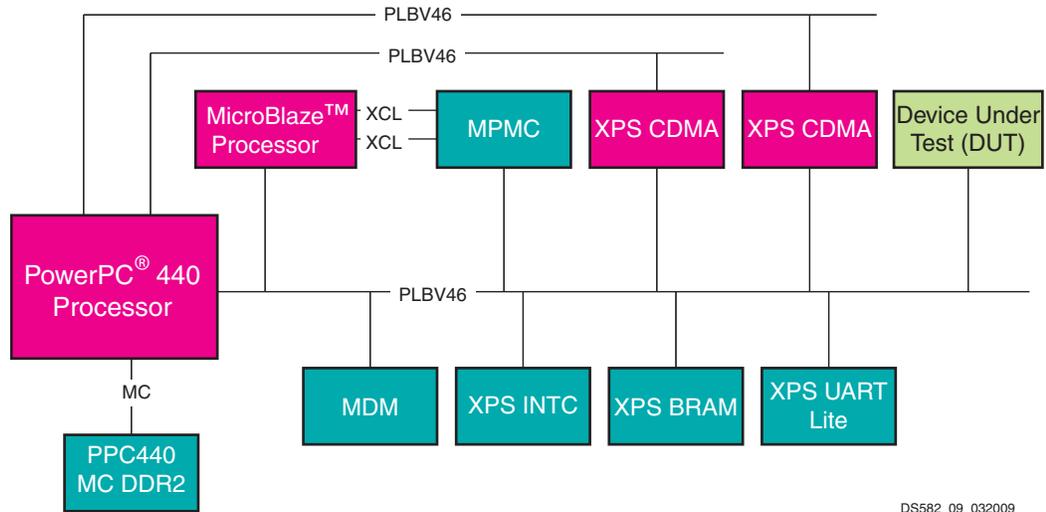


Figure 9: Virtex-5FX System

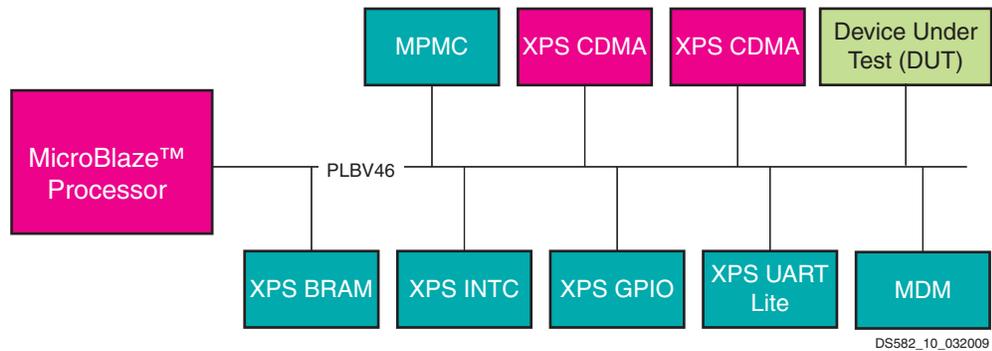


Figure 10: Spartan-3A System

The target FPGA was then filled with logic to drive the LUT and BRAM utilization to approximately 70% and the I/O utilization to approximately 80%. Using the default tool options and the slowest speed grade for the target FPGA, the resulting target F_{MAX} numbers are shown in Table 14.

Table 14: XPS XPS Timer/Counter System Performance

Target FPGA	Target F_{MAX} (MHz)
S3A700 -4	90
V4FX60 -10	100
V5FXT50 -1	120

The target F_{MAX} is influenced by the exact system and is provided for guidance. It is not a guaranteed value across all systems.

Support

Xilinx provides technical support for this LogiCORE product when used as described in the product documentation. Xilinx cannot guarantee timing, functionality, or support of product if implemented in devices that are not defined in the documentation, if customized beyond that allowed in the product documentation, or if changes are made to any section of the design labeled *DO NOT MODIFY*.

Reference Documents

The following documents contain information that may be required in understanding the XPS Timer/Counter reference design:

1. *IBM CoreConnect 128-Bit Processor Local Bus: Architecture Specifications* version 4.6

Revision History

Date	Version	Revision
11/10/06	1.0	Initial Xilinx release.
4/20/07	1.1	Added SP-3 support.
9/26/2007	1.2	Added FMax Margin System Performance section.
11/27/2007	1.3	Added SP-3A DSP support.
1/14/08	1.4	Added Virtex-II Pro support.
4/21/08	1.5	Added Automotive Spartan-3E, Automotive Spartan-3A, Automotive Spartan-3, and Automotive Spartan-3A DSP support.
7/24/08	1.6	Added QPro Virtex-4 Hi-Rel and QPro Virtex-4 Rad Tolerant FPGA support.
12/15/08	1.7	IPIF update. Library change from proc_common_v2_00_a to proc_common_v3_00_a and Plbv46_slave_single_v1_00_a to Plbv46_slave_single_v1_01_a.
4/24/09	1.8	Replaced references to supported device families and tool name(s) with hyperlink to PDF file.
6/25/09	1.9	Added S6/V6 Resource utilization tables and systems and also updated Fmax numbers.

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